





Work at HIT as lecturer after graduation

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I) Where am I from?

Education Background

2001-2005

B.S. HIT

2005-2007

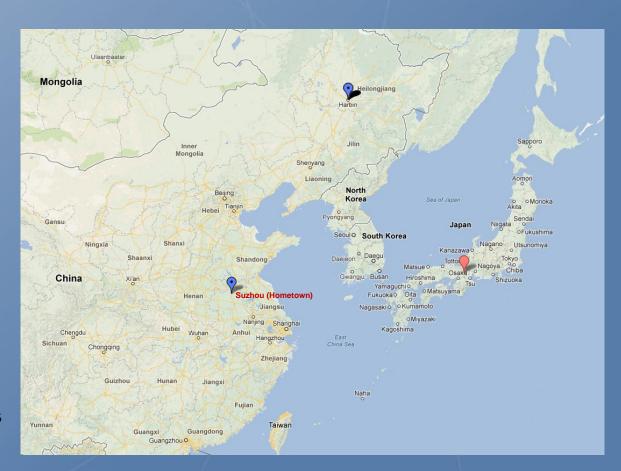
M.S. HIT

2007-2010

Ph.D. Ritsumeikan Ma Laboratory

2011-

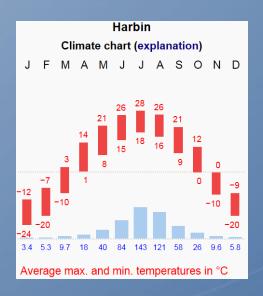
Lecturer, HIT School of Mechatronics Engineering

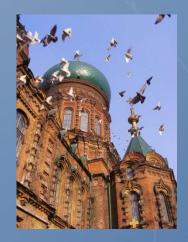


I) Where am I from?

Harbin 哈尔滨

Nickname(s):
Ice City,
Oriental Paris,
Oriental Moscow





Russian Orthodox Saint Sofia Church built in 1907



Harbin Xinhua Bookstore



Tower at Harbin Ice and Snow Festival 2013



Photographed by Atsushi Kakogawa

Harbin Institute of Technology

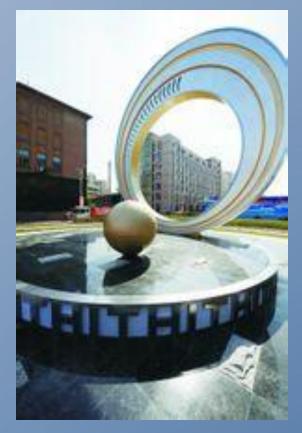
- A member of the C9 League
- First-level institute of Technology in China
- To cultivate intellectuals and engineers for industry



School Badge



Motto: Strict and Standard, Greatest Effort



Statue of Minor Planet in campus

- □ 55838 Hagongda (provisional designation: 1996 LN) is a main-belt minor planet.
- ☐ It was discovered through the Beijing Schmidt CCD Asteroid Program at the Xinglong Station in the Yan Mountains of China on June 7, 1996.
- ☐ It is named after the Harbin Institute of Technology, nicknamed *Hagongda*.





Main building of Russian-style (built in 1950s)

Schools of HIT (Science, Engineering, and Architecture)

School of Astronautics

School of Mechatronics Engineering

School of Material Science and Engineering

School of Energy Science and Engineering

School of Electrical Engineering and Automation

School of Civil Engineering

School of Municipal and Environmental Engineering

School of Architecture

Schools of HIT (Humanity, social science, and management)

School of Management

School of Humanities and Social Sciences

School of International Relations of Economics and Trade

School of Law

School of Foreign Languages

Research Center of Aerospace Mechanism and Control



- Research related to Lunar exploration in China
- ☐ Innovative mechanisms with light-weight, low-power, high-reliability
- Close relationship with National Aerospace Departments

Lunar Exploration of China (Chang'e Mission)





Circling Landing Returning

Phase I: Circling

> Satellite (2007)

Phase II: Landing

Lunar Rover (2013)

Phase III: Returning

➤ Automated Sampling Device (2017)

Lunar Rovers with Different Configurations





Rocker-bogie Rover



Rover with symmetric suspension



Negotiating obstacles



Closed-chain rover



Gravity center changeable rover



Multi-joint wheeled-walking rover





Rover with torsional bar



6-wheeled rocker-bogie rover

Rover Wheels with Different Shapes

Phase II





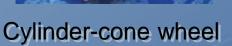




Light weight wheels

Cylinder wheels







Drum wheel



Straight rug



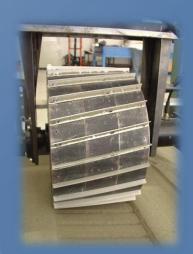
Inclined rug

Test-bed to evaluate the performance of wheels

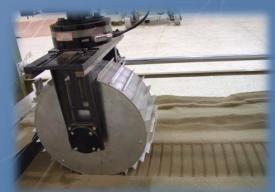
Phase II

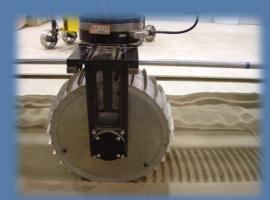












III) My Research Interests

2005-2007

RCAMC, HIT

Master thesis:

Development of a test-bed for wheel -soil interaction and experimental study



2007-2010

Ma Laboratory, Ritsumeikan

Doctoral thesis:

Analysis of a Crawler Robot with Environmentally-adapted Mobility and its Modular Design







III) My Research Interests

2011-present

RCAMC, HIT

- Intelligent Drilling Strategy Based on Recognition
- USDC(Ultrasonic Driller and Corer)



Drilling test-bed

Drilling Experiments



USDC

IV) Working Experience

Positions for young doctors at HIT

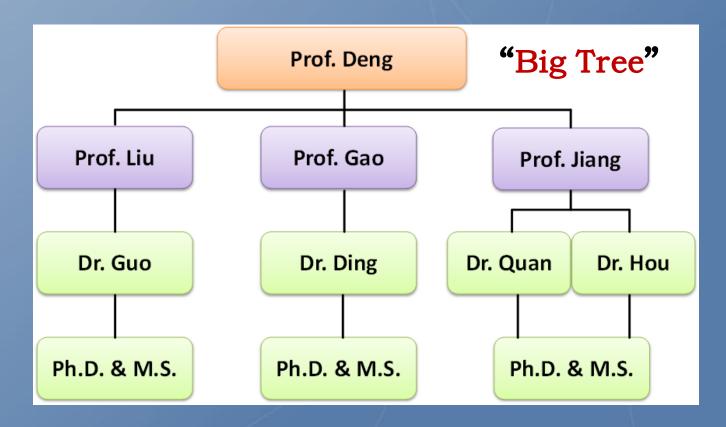
Three types:

Research & Education

Research

IV) Working Experience

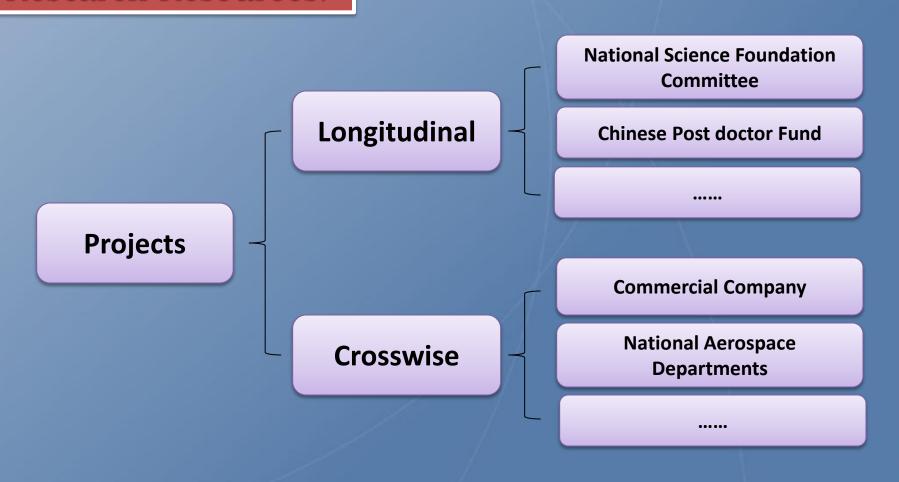
Personnel of RCAMC



"Laboratory Tree"

IV) Working Experience

Research Resources:



V) Advice for Juniors

Japanese Students:

- > Research, Research, Research.
- ➤ NO research, NO position.

Resident Students:

1.Work in Japan

- Research, Research, Research.
- Improve Japanese Level.

2. Return Motherland

- Project, Project, Project.
- NO project, NO research.

Acknowledgement

- Professor Ma
- Professor Hirai
- Professor Maeda
- Professor Kawamura
- Professor Ozawa
- Professor Nokata
- Members of Ma Laboratory
- Members of Hirai Laboratory
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- Friends at Ritsumeikan









Thanks for your attention!